

Series CGPT self-centering parallel grippers with T-guide

Single and double acting, magnetic, self-centering Bores: Ø 16, 20, 25, 32, 40 mm







Thanks to the use of a high performing and precise force transmission system, the Series CGPT grippers are able to provide high gripping forces while guaranteeing a very high repeatability.

The wide range of sizes available allows you to find the best solution for any need of movement. The grippers are supplied with centering bushes (tolerance H8) which, once positioned on the body and/or on the jaws, are able to guarantee, during maintenance, a high interchangeability of the gripper and of the extensions.

- » Robust, compact and light design
- » High closing/opening forces
- » Fixing from the top, from below and from the side
- » Supply on the side or on the bottom (even without using tubes)
- » Self-centering jaws
- » High closing and opening repeatability
- » High interchangeability (centering bushes)
- » Position detection thanks to the use of magnetic proximity switches.
- » In compliance with ROHS directive
- » PTFE, Silicone and Copper free
- » High reliability
- » High resistance to external loads thanks to the T-guide
- » Variants available for use in ATEX zones and for high temperatures

GENERAL DATA

Type of constructionSelf-centering parallel gripper with T-guide
Operation
Single acting (NO, NC), double acting

Bores Ø16, 20, 25, 32, 40 mm

Force transmission Lever

Air connections M3 (Ø16), M5 (Ø20, 25, 32), G1/8 (Ø40)

Working pressure $2 \div 8$ bar (double acting), $4 \div 8$ bar (single acting)

Working temperature 5°C ÷ 60°C (standard) - 5°C ÷ 150°C (high temperature version)

Store temperature -10°C ÷ 80°C

 $\textbf{Maximum use frequency} \quad \text{3 Hz } (\emptyset\ 16,20,25,32), \text{2 Hz } (\emptyset\ 40)$

Repeatability 0.02 mm Interchangeability 0.1 mm

Medium Filtered air in class 7.4.4 according to ISO 8573-1. In case lubricated air is used, we recommend ISOVG32 oil and to never interrupt

lubrication.

Lubrication After 10 million cycles, grease the sliding zones using Molykote DX grease.

Protection class IP 40
Compatibility ROHS Directive

Certifications ATEX (II 2GD c IIC 120°C(T4)-20°C≤Ta≤80)

Materials PTFE, Silicone and Copper free

N.B. Pressurize the pneumatic system gradually in order to avoid uncontrolled movements

EX



CODING EXAMPLE

CGPI	-	16	-	NC	-	W	EX
CGPT	SERIES						
16	BORES: 10 = Ø 10 mm 16 = Ø 16 mm 20 = Ø 20 mm 25 = Ø 25 mm 32 = Ø 32 mm 40 = Ø 40 mm						
NC	FUNCTIONING: = double acting				PNEUMATIC SYMBOL PNZ1	S	

PNZ3 PNZ2

= double acting
NO = single acting, normally open
NC = single acting, normally closed

VERSION:
= standard
W = high temperatures (150 °C) - not magnetic

Add EX to order the certified ATEX version

PNEUMATIC SYMBOLS

The pneumatic symbols which have been indicated in the CODING EXAMPLE are shown below.

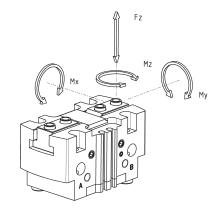






Maximum admissible loads and torques

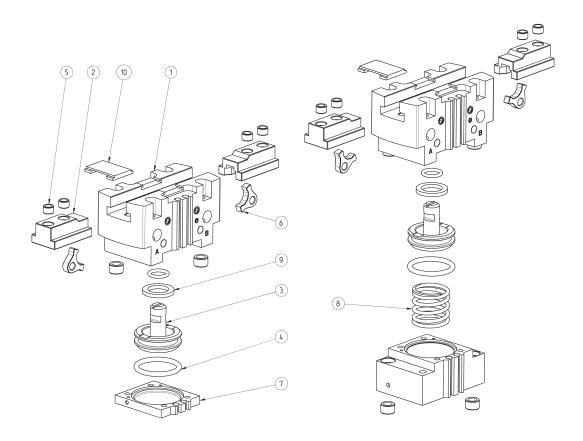
Fz s, Mx s, My s, Mz s =
maximum admissible loads and
torques in static conditions
Fz d, Mx d, My d, Mz d =
maximum admissible loads and
torques in dynamic conditions



Mod.	Fzs(N)	Mx s (Nm)	My s (Nm)	Mz s (Nm)	Fz d (N)	Mx d (Nm)	My d (Nm)	Mz d (Nm)
CGPT-16	200	2.5	2.5	2	2	0.06	0.06	0.06
CGPT-20	350	5	7.5	4	4	0.12	0.12	0.12
CGPT-25	600	8	13	6.5	6	0.25	0.25	0.25
CGPT-32	900	18	30	15	9	0.5	0.5	0.5
CGPT-40	1500	40	60	30	15	1	1	1

CAMOZZI Automation

Series CGPT grippers - construction



LIST OF COMPONENTS		
PARTS	MATERIALS	
1 - Body	Aluminium	
2 - Jaw	Stainless steel	
3 - Piston	Stainless steel	
4 - Seals	HNBR / FKM	
5 - Centering bushes	Stainless steel	
6 - Levers	Steel	
7 - End cover	Aluminium	
8 - Spring	Stainless steel	
9 - Magnet	Neodymium	
10 - Cover	Stainless steel	

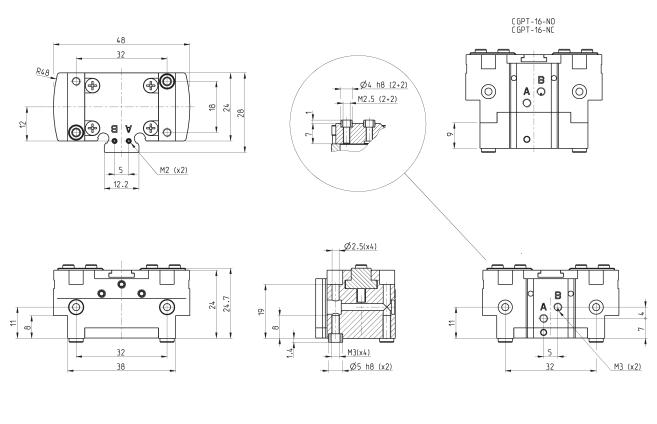


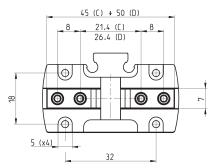
CGPT gripper, size 16 mm - dimensions

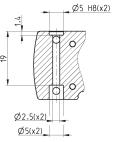


- A = Opening of air connection
- B = Closing of air connection C = Closed gripper









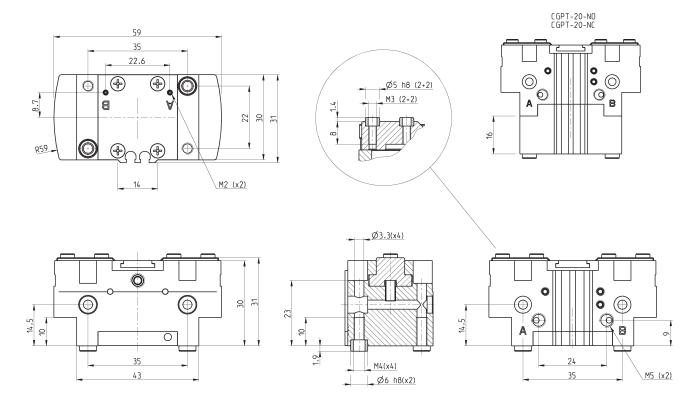
Mod.	Total closing gripping	Closing gripping force T	otal opening gripping	Opening gripping force	Stroke per	Working	Working	Repeatability	Max use	Weight
	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	frequency (Hz)	(Kg)
CGPT-16	114	57	130	65	2.5	2 ÷ 8	5 ÷ 60	0.02	3	0.09
CGPT-16-NC	142	71	90	45	2.5	4 ÷ 8	5 ÷ 60	0.02	3	0.11
CGPT-16-NO	74	37	160	80	2.5	4 ÷ 8	5 ÷ 60	0.02	3	0.1

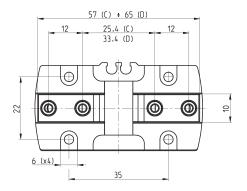
C₹ CAMOZZI

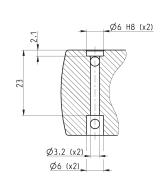
CGPT gripper, size 20 mm - dimensions



- A = Opening of air connection
- B = Closing of air connection C = Closed gripper
- D = Open gripper







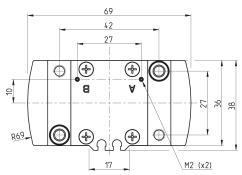
Mod.	Total closing gripping force at 6 bar (N)	g Closing gripping force T each jaw at 6 bar (N)	otal opening gripping force at 6 bar (N)	Opening gripping force each jaw at 6 bar (N)				Repeatability	Max use frequency (Hz)	Weight) (Kg)
CGPT-20	166	83	188	94	4	2 ÷ 8	5 ÷ 60	0.02	3	0.15
CGPT-20-NC	208	104	102	51	4	4 ÷ 8	5 ÷ 60	0.02	3	0.2
CGPT-20-NO	102	51	246	123	4	4 ÷ 8	5 ÷ 60	0.02	3	0.18

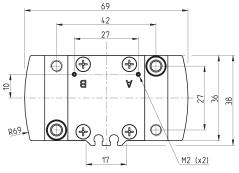


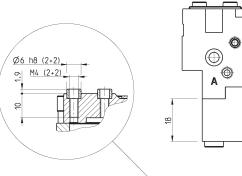
CGPT gripper, size 25 mm - dimensions

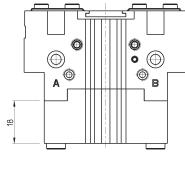


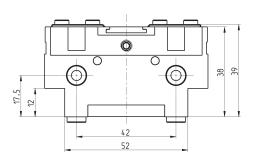
- A = Opening of air connection
- B = Closing of air connection C = Closed gripper
- D = Open gripper

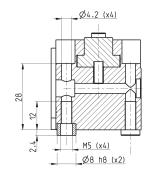


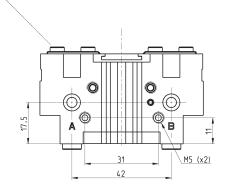


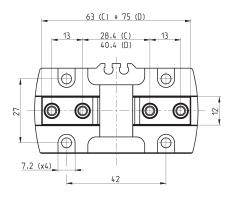


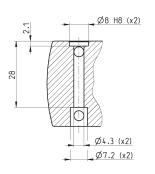












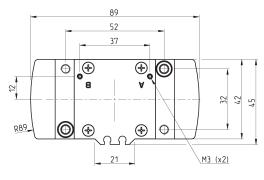
Mod.	Total closing gripping	Closing gripping force T	otal opening gripping	Opening gripping force	Stroke per	Working	Working	Repeatability	Max use	Weight
	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	frequency (Hz)	(Kg)
CGPT-25	236	118	280	140	6	2 ÷ 8	5 ÷ 60	0.02	3	0.27
CGPT-25-NC	286	143	206	103	6	4 ÷ 8	5 ÷ 60	0.02	3	0.35
CGPT-25-NO	166	83	330	165	6	4 ÷ 8	5 ÷ 60	0.02	3	0.33

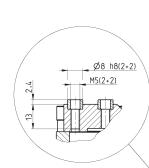
C₹ CAMOZZI

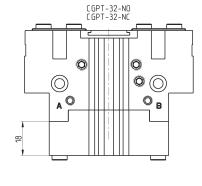
CGPT gripper, size 32 mm - dimensions

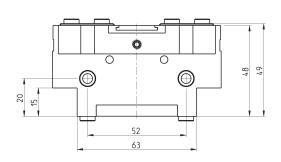


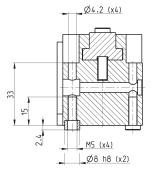
- A = Opening of air connection
- B = Closing of air connection C = Closed gripper
- D = Open gripper

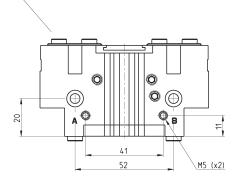


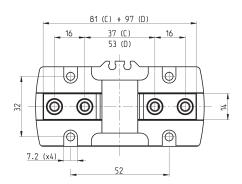


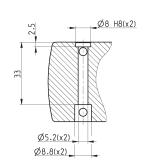












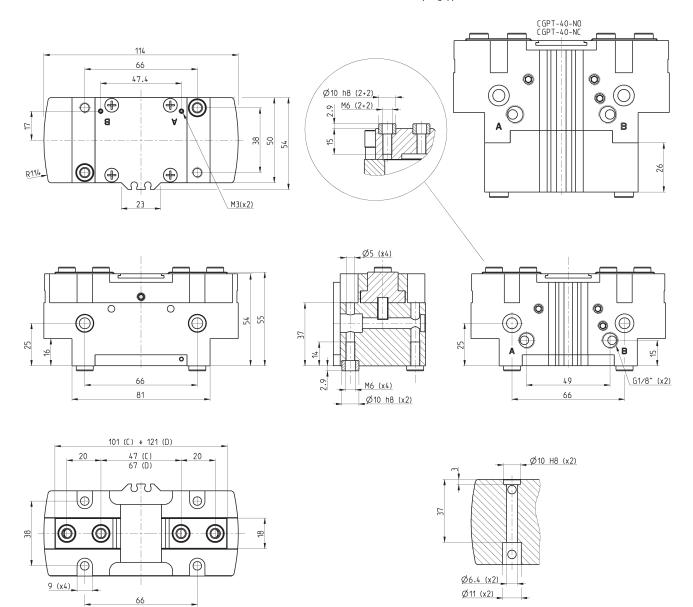
Mod.	Total closing gripping force at 6 bar (N)	g Closing gripping force T each jaw at 6 bar (N)	otal opening gripping force at 6 bar (N)	Opening gripping force each jaw at 6 bar (N)				Repeatability (mm)	Max use frequency (Hz)	Weight) (Kg)
CGPT-32	386	193	450	225	8	2 ÷ 8	5 ÷ 60	0.02	3	0.5
CGPT-32-NC	454	227	354	177	8	4 ÷ 8	5 ÷ 60	0.02	3	0.61
CGPT-32-NO	294	147	520	260	8	4 ÷ 8	5 ÷ 60	0.02	3	0.59



CGPT gripper, size 40 mm - dimensions



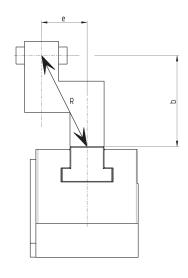
- A = Opening of air connection
- B = Closing of air connection C = Closed gripper
- D = Open gripper

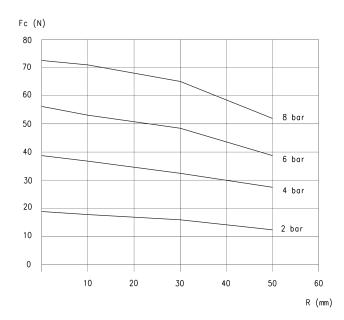


Mod.	Total closing gripping force at 6 bar (N)	Closing gripping force 1 each jaw at 6 bar (N)	otal opening gripping force at 6 bar (N)	Opening gripping force each jaw at 6 bar (N)			Working temperature (°C)	Repeatability (mm)	Max use frequency (Hz)	Weight) (Kg)
CGPT-40	670	335	720	360	10	2 ÷ 8	5 ÷ 60	0.02	2	0.83
CGPT-40-NC	780	390	504	252	10	4 ÷ 8	5 ÷ 60	0.02	2	1.2
CGPT-40-NO	446	223	826	413	10	4 ÷ 8	5 ÷ 60	0.02	2	1.1

CAMOZZI Automation

GRIPPING FORCE (Fc) PER SINGLE JAW





The total gripping force has to be calculated as follows: Total $Fc = Fc \times 2$

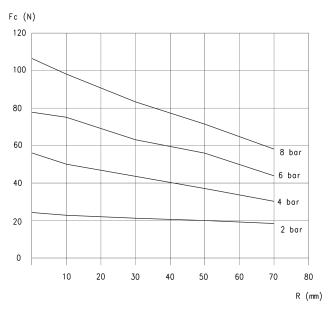
Gripping force in relation to the lever arm (R) and the eccentricity (b, e)

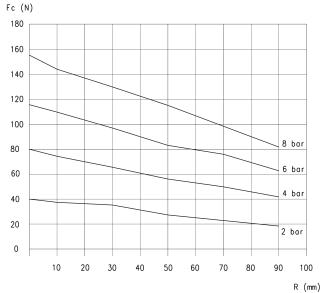
$$R = \sqrt{(b^2 + e^2)}$$

CGPT-16

R = lever arm Fc = closing gripping force

Fa (opening gripping force) = Fc + 10%





CGPT-20

R = lever arm Fc = closing gripping force

Fa (opening gripping force) = Fc + 10%

CGPT-25

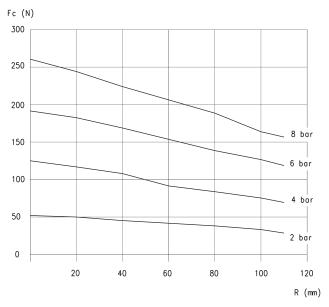
R = lever arm

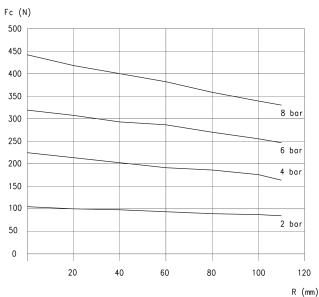
Fc = closing gripping force

Fa (opening gripping force) = Fc + 10%



GRIPPING FORCE (Fc) PER SINGLE JAW





CGPT-32

R = lever arm

Fc = closing gripping force

Fa (opening gripping force) = Fc + 10%

CGPT-40

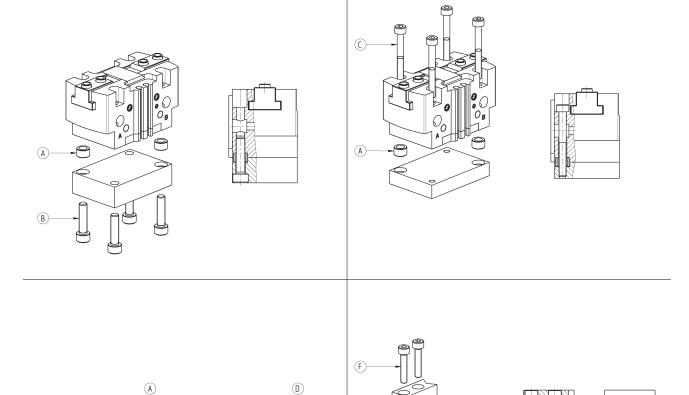
R = lever arm

Fc = closing gripping force

Fa (opening gripping force) = Fc + 10%

CAMOZZI Automation

Examples of mounting

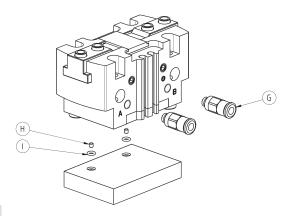


(E)

Mod.	Α	В	С	D	E	F
CGPT-16	Ø5	M3	M2.5	M2.5	Ø4	M2.5
CGPT-20	Ø6	M4	M3	М3	Ø5	M3
CGPT-25	Ø8	M5	M4	M4	Ø6	M4
CGPT-32	Ø8	M5	M4	M5	Ø8	M5
CGPT-40	Ø10	M6	M5	M6	Ø10	M6



Air supply ports



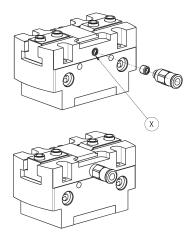
Mod.	G	Н	1
CGPT-16	M3	M2	OR 1x2.5
CGPT-20	M5	M2	OR 1x2.5
CGPT-25	M5	M2	OR 1x2.5
CGPT-32	M5	M3	OR 1x3.5
CGPT-40	G1/8	M3	OR 1x3.5

Example of use of the pressurization/lubrication hole

Example of use of the lubrication (greasing) or pressurization hole of the zone with moving items

NOTE 1: grease the sliding zones using Molykote DX grease.

NOTE 2: supply a pressure of max. 3 bar in order to avoid the sudden ejection of grease.

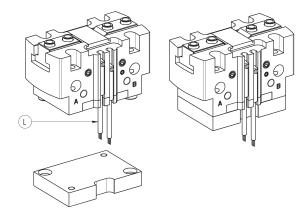


Mod.	Х	
CGPT-16	M3	
CGPT-20	M5	
CGPT-25	M5	
CGPT-32	M5	
CGPT-40	M5	

Example of mounting: sensors

L = sensor mod. CSD-332 or mod. CSD-362

In order to position the sensor correctly, a channel must be created in the base.

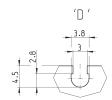


Mod.
CGPT-16
CGPT-20
CGPT-25
CGPT-32
CGPT-40

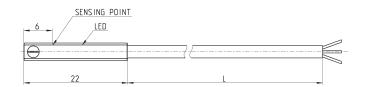


Series CSD magnetic proximity switches with 3-wire cable







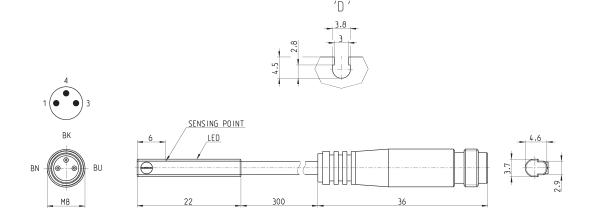


Mod.	Operation	Connections	Voltage	Output	Max. current	Max Load	Protection	L = length cable
CSD-332	Electronic	3 wires	10 ÷ 27 V DC	PNP	200 mA	6W	Against polarity reversing and overvoltage	2 m

Series CSD magnetic proximity switches with male connector M8

Length of cable 0.3 metres





Mod.	Operation	Connection	Voltage	Output	Max. current	Max load	Protection
CSD-362	Electronic	3 wires with M8 connector	10 ÷ 27 V DC	PNP	200 mA	6W	Against polarity reversing and overvoltage